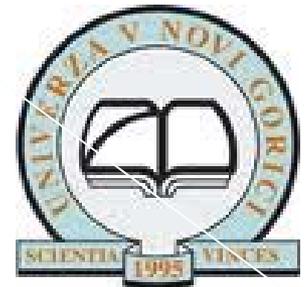

Characterization of ionospheric effects on GNSS systems

Marko Vučković

Centre for Atmospheric
Research
University of Nova Gorica



OUTLINE

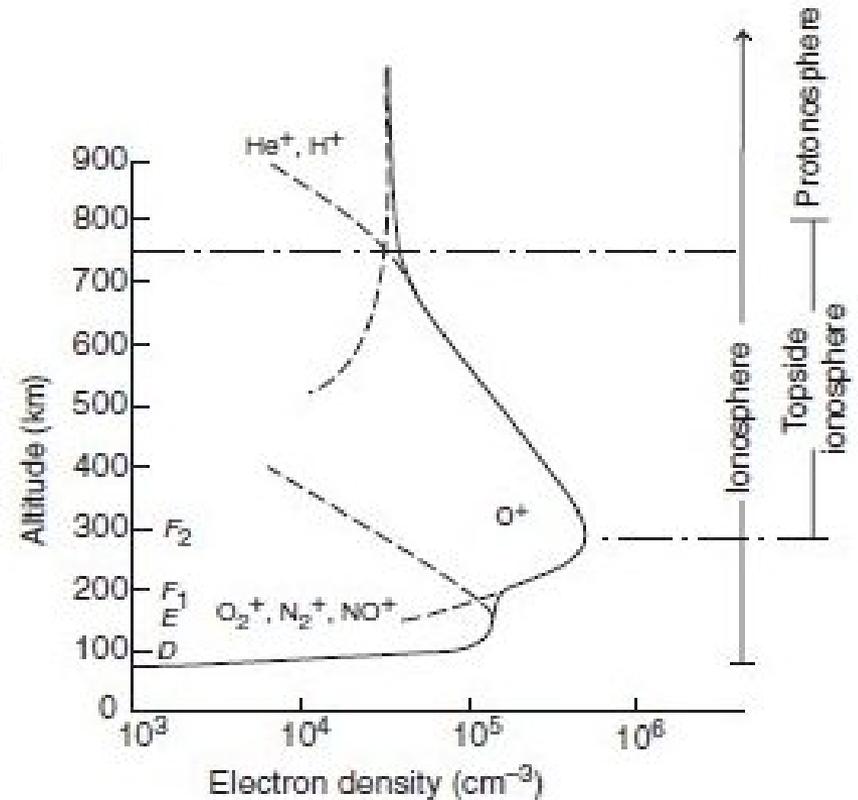
- **The Ionosphere**
- The GNSS
- The ionospheric effects on GNSS signals
- Methods to reduce the ionospheric impact on GNSS
- Future goals

The Ionosphere

- Is the upper part of the Earth's atmosphere that is ionized by solar radiation
- Extends from about 60 to 1000 km and completely encircles the Earth.

The ionosphere has been divided into three main layers (regions): the D, E, and F regions:

- (the lowest) D-region: 50-90 km, relatively weak ionization due to its position at the bottom,
- E-region: 90-150 km, contains mostly O_2^+ and NO^+ ions, with metallic long lived ions to a minor extent,
- F-region: 150-1000 km contains a range of ions from NO^+ and O^+ at the bottom to H^+ and He^+ ions at the top. Electron density reaches an absolute maximum in this region (F2 layer).



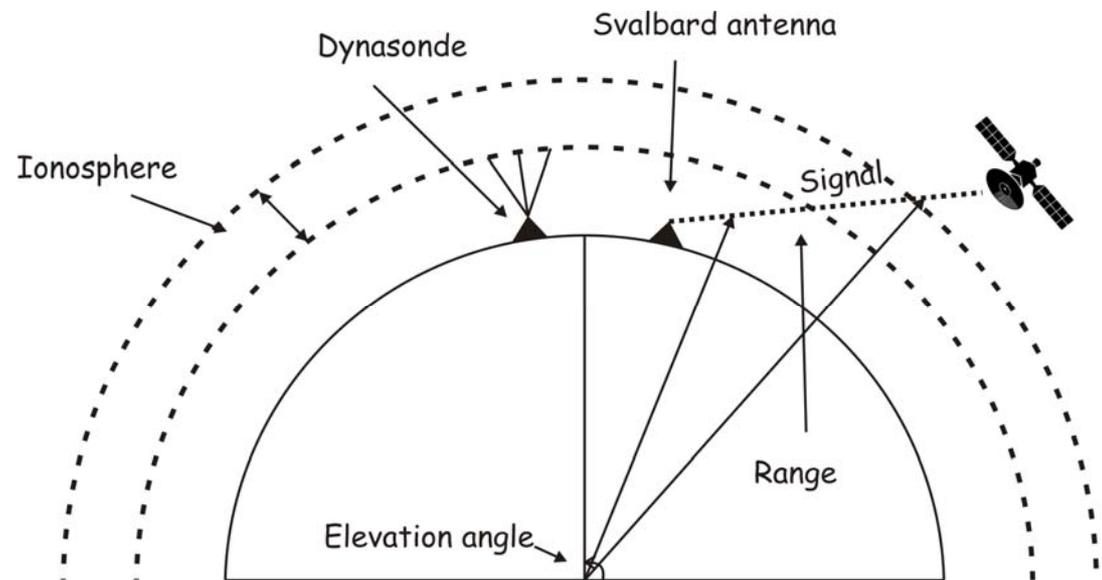
Banks, P. M., R. W. Schunk, and W. J. Raitt, The topside ionosphere: the region of dynamic transition, *Ann. Rev. Earth Planet. Sci.*, 4, 381, 1976.

The Ionosphere

- The EISCAT measurements were done to observe parameters:
 - Ne
 - Ti
 - Te/Ti
 - Vi

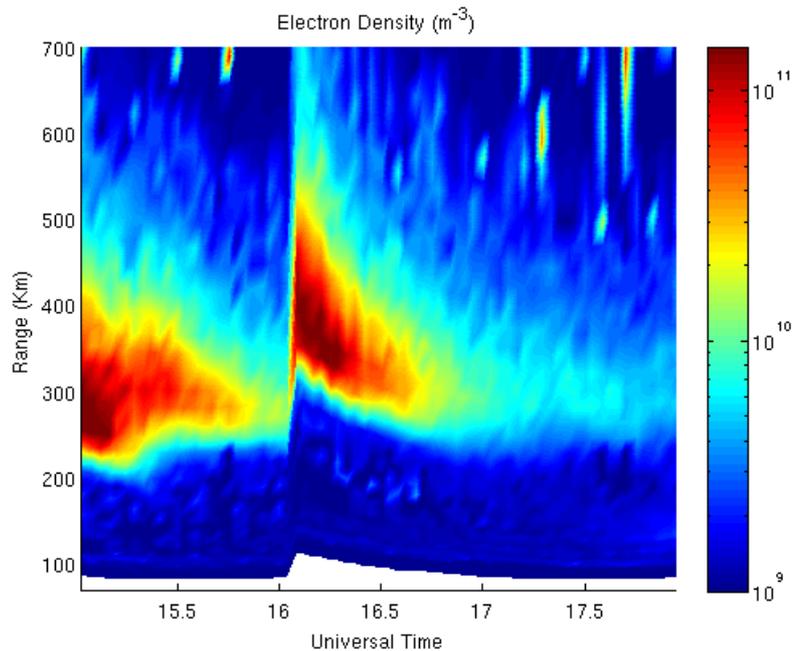


Fixed 42 m and steerable 32 m UHF parabolic antennas, Svalbard



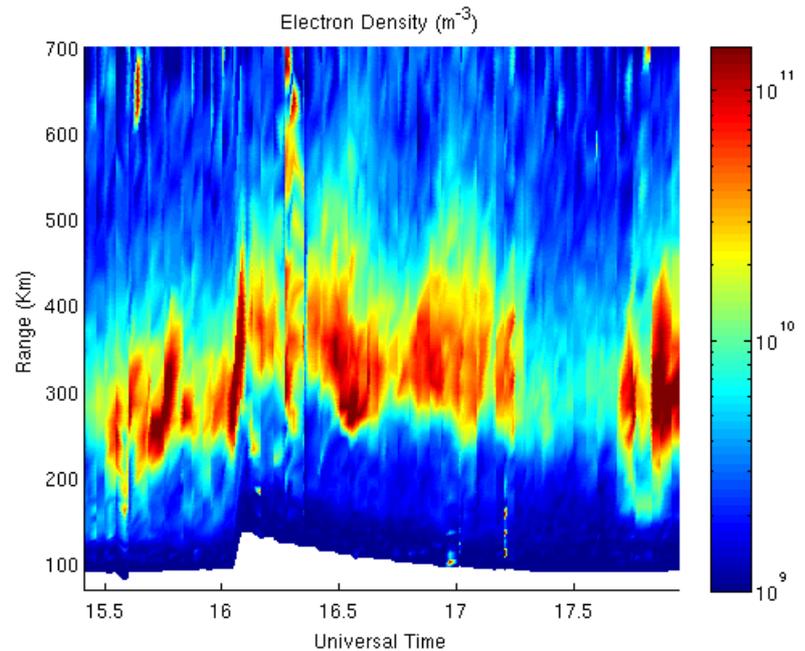
Experimental setup

The Ionosphere



**Electron density,
Tromsø, 13.12.11.**

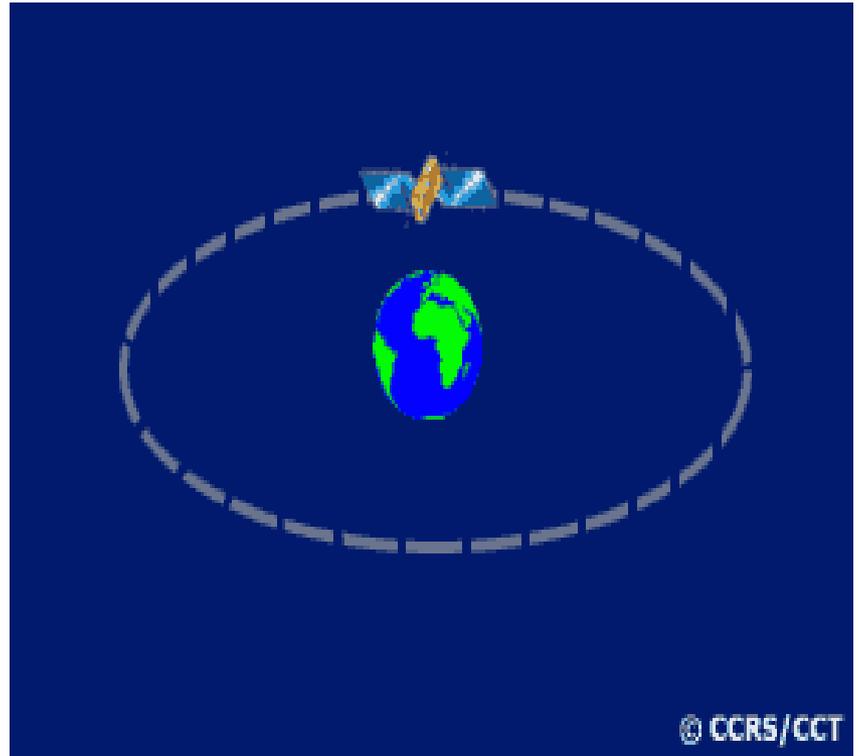
**Electron density,
Svalbard, 13.12.11**



-
- The Ionosphere
 - **The GNSS**
 - The ionospheric effects on GNSS signals
 - Methods to reduce the ionospheric impact on GNSS
 - Future goals

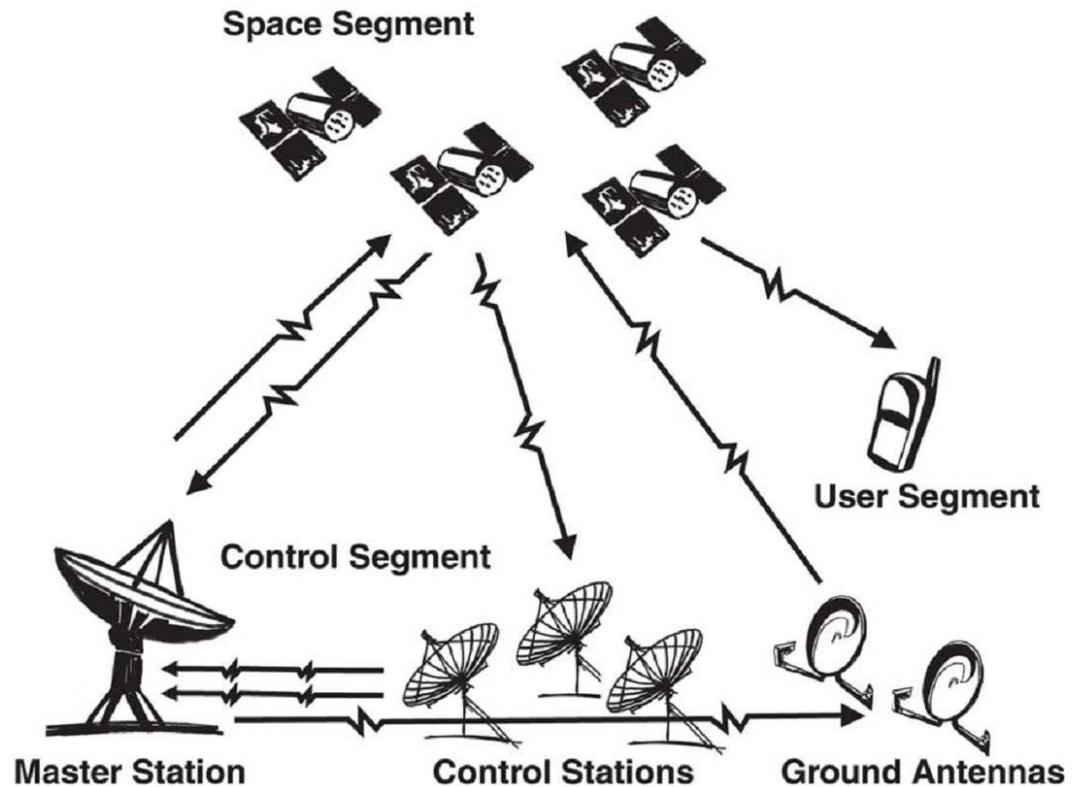
The GNSS

- GNSS - Global Navigation Satellite System:
 - GPS
 - GLONASS
 - Galileo
 - COMPASS



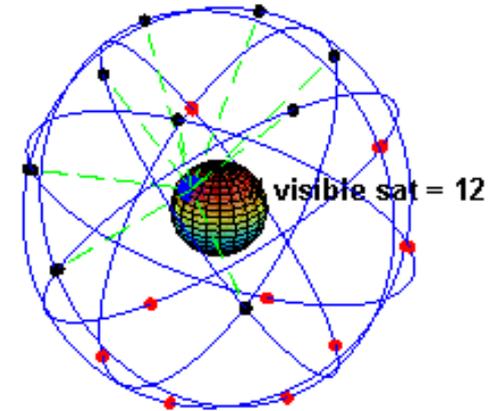
The GNSS

- GPS - Global Positioning System
- The GPS system consists of three segments:
 - Space segment
 - Control segment
 - User segment



The GNSS

- About 30 satellites
- Altitude of about 20200 km
- Distributed among 6 orbital planes
- One master control station
- Five monitor stations
- Ground antennas



Peter H. Dana 5/27/95



Global Positioning System (GPS) Master Control and Monitor Station Network

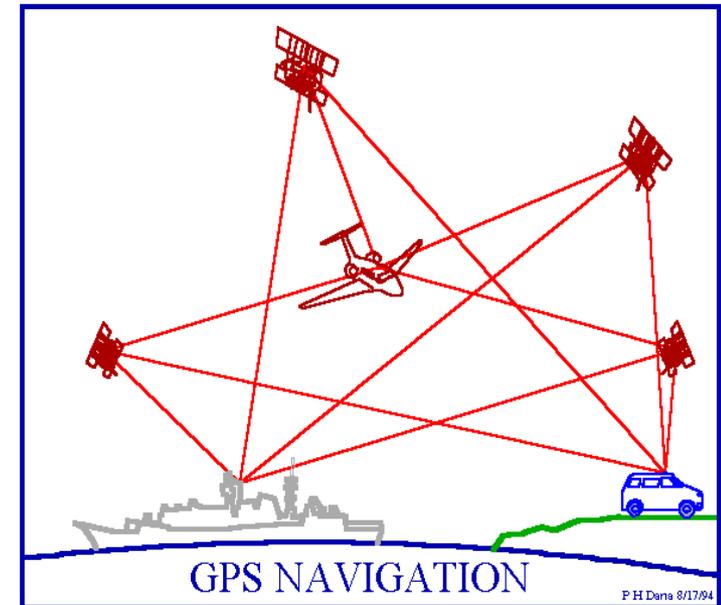
- Applications:
 - navigation
 - aviation
 - geodesy
 - survey



The GNSS

How does it work?

- Four satellites are required.
- GPS satellites transmit signals to GPS receivers on the ground.
- The exact location and current time is transmitted from each GPS satellite.
- GPS receivers convert satellite's signals into position, velocity, and time estimates.



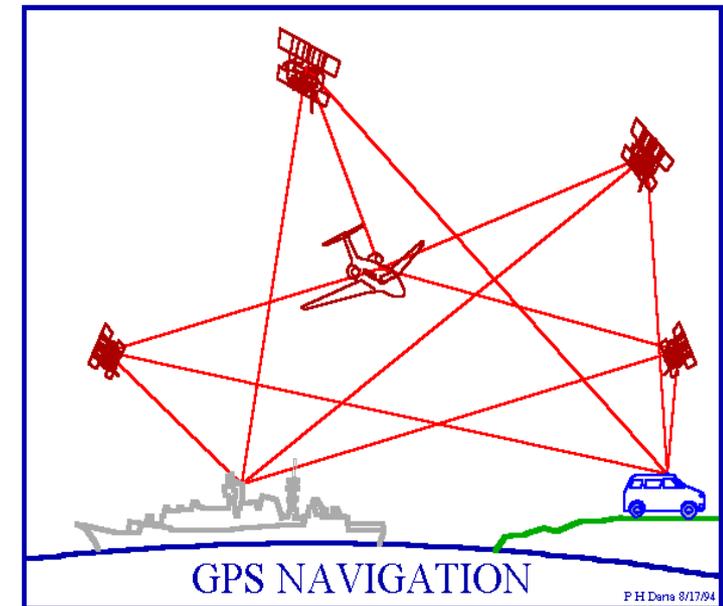
The GNSS

How does it work?

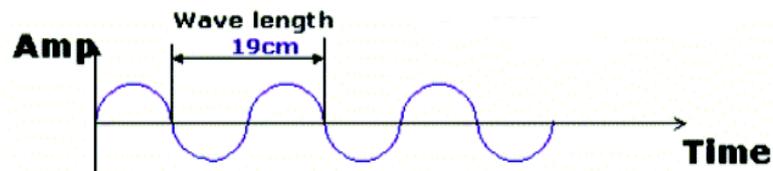
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Signal structure:

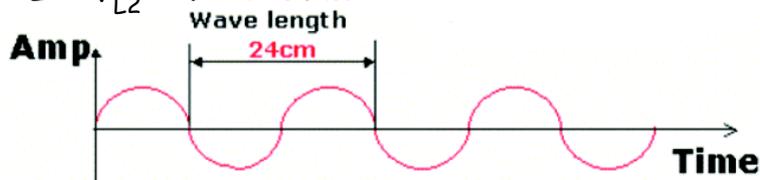
- Carrier
- Navigation data
- Ranging code (pseudorandom codes, PRN):
 - C/A (Coarse Acquisition code)
 - P (Precise code)



L1: $f_{L1} = 1.575 \text{ GHz}$



L2: $f_{L2} = 1.227 \text{ GHz}$



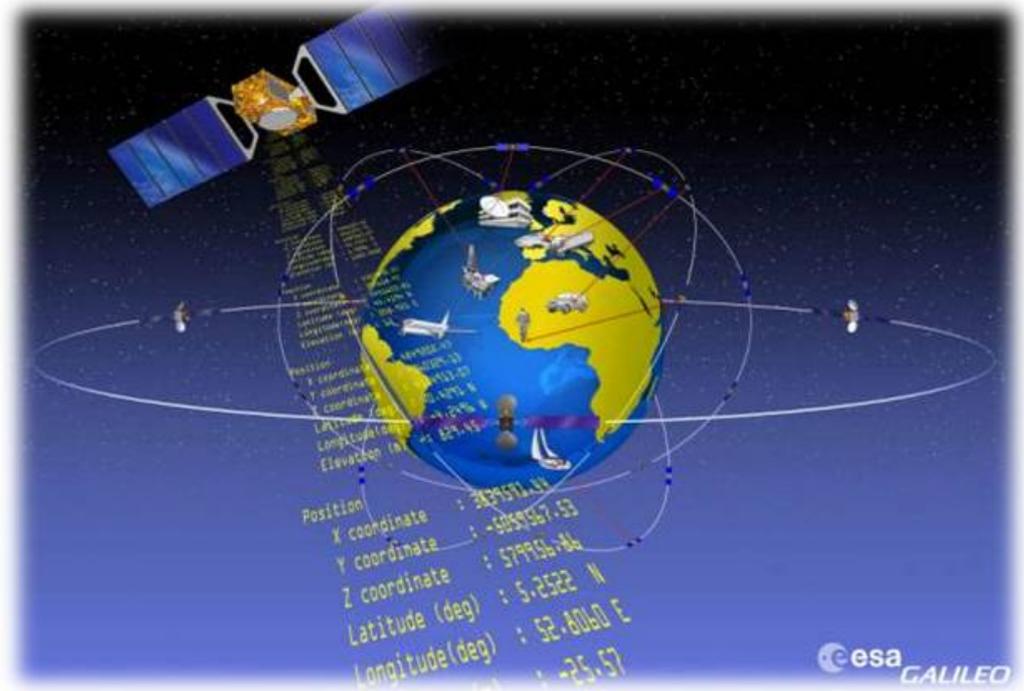
The GNSS

GALILEO

- 27 satellites (+3 spares)
- Emits 3 frequencies:
 - E5, E6, E1

GLONASS

- 21 satellites (+ 3 active spares)
- Altitude: 19,100 km
- 3 orbital planes
- Emits two frequencies:
 - L1
 - L2



The GNSS

New GNSS signals

- **GPS III:**

- L2C ($f_{L2}=1222,6$ MHz)
- L5 ($f_{L5}=1176,5$ MHz, two PRN codes)
- L1C ($f_{L1}=1575,4$ MHz, interoperability with Galileo L1)

- **GALILEO:**

- L1 ($f_{L1}=1575,4$ MHz)
- E6 ($f_{E6}=1278,75$ MHz)
- E5 (E5a ($f_{E5a}=1176,45$ MHz) and E5b ($f_{E5b}=1207,14$ MHz))

- **GLONASS:**

- L1OC ($f_{L1}=1602$ MHz, between 1597 and 1617 MHz)
- L2OC ($f_{L2}=1246$ MHz, between 1240 and 1260 MHz)

The GNSS

Modulation schemes

- **GPS:**

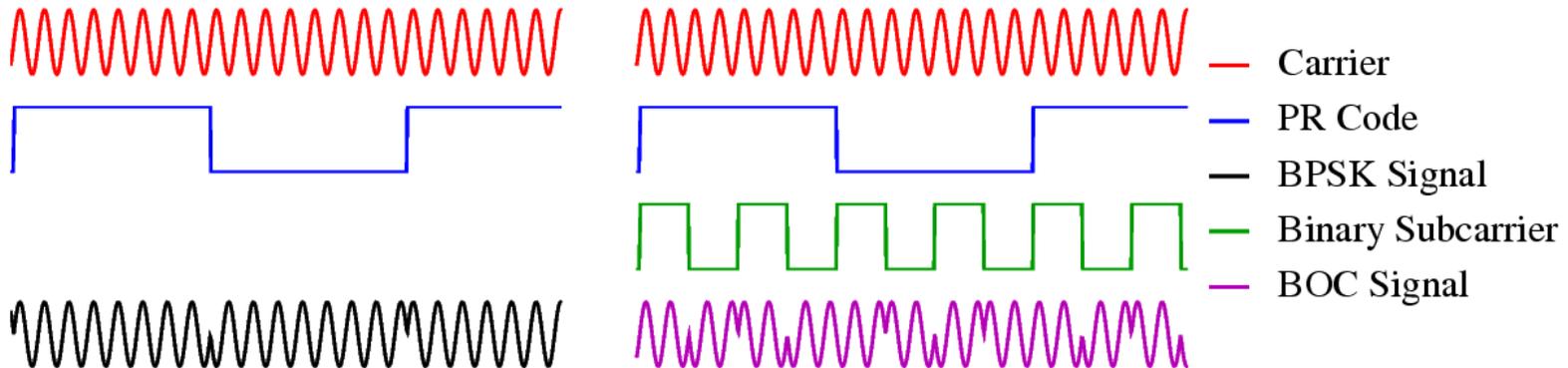
- TMBOC(6,1,1/11)
- BPSK-R(10)

- **GALILEO:**

- AltBOC(15,10)
- CBOC(6,1,1/11)

- **GLONASS:**

- BPSK-R(1)



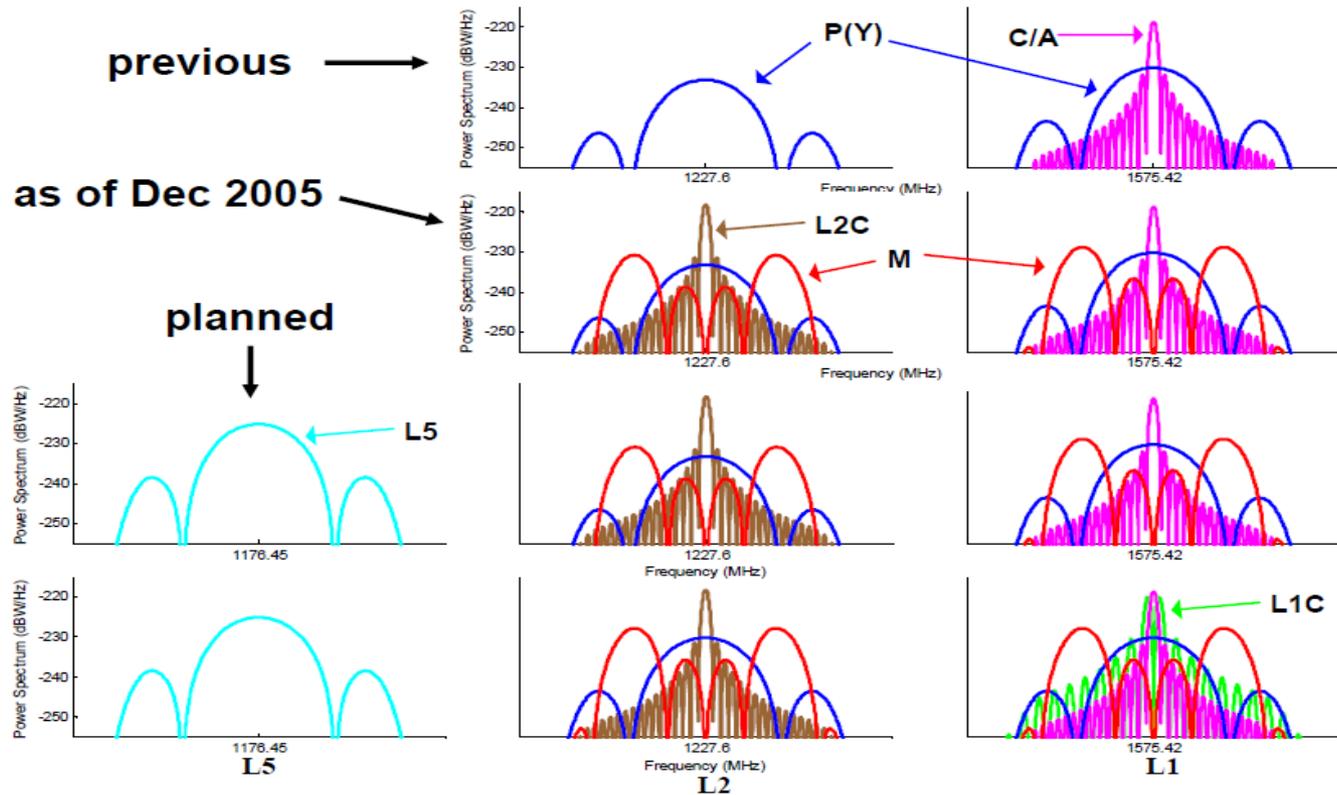
- **Improvements:**

- More signal power.
- Better multi-path mitigation capabilities.
- More robust navigation.

The GNSS

GPS III SIGNALS

GPS frequency spectrum



Block IIA, 1990



Block IIR-M, 2005



Block IIF, 2009



Block III, 2014

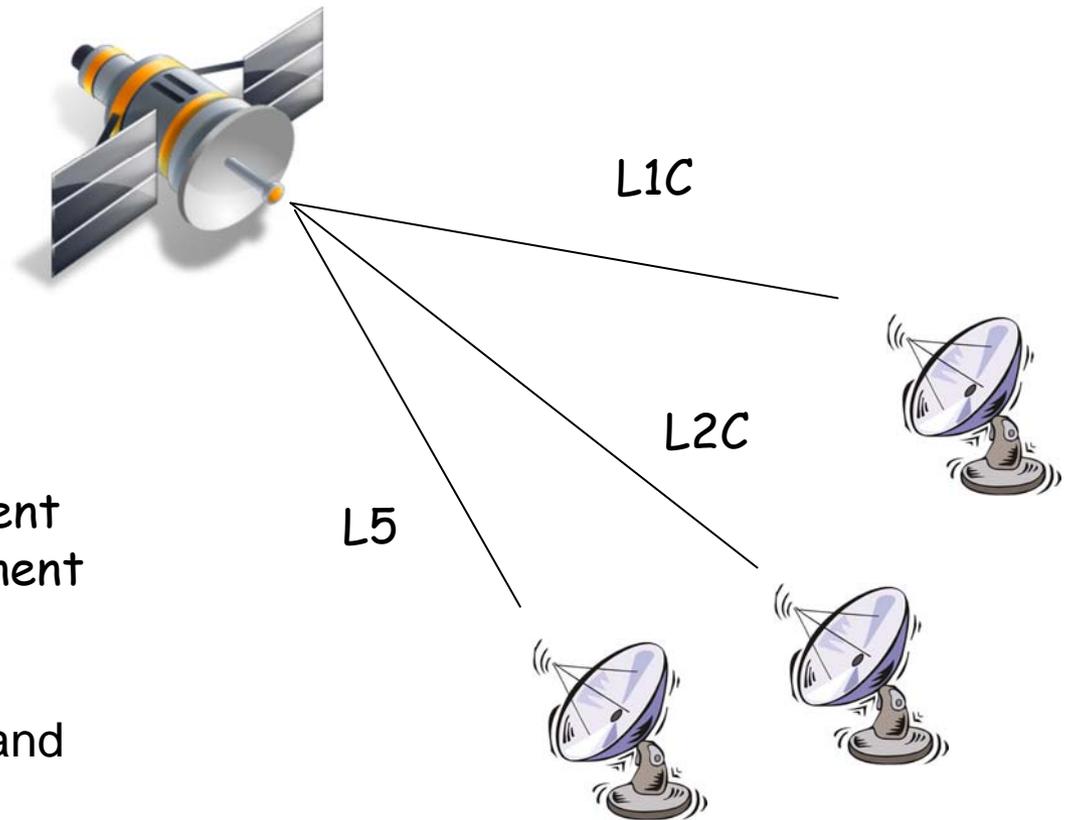


(artist's concept)

The GNSS

GPS III SIGNALS

- Characteristics of new GPS signals:
 - Different PRN codes
 - Longer codes
 - Faster codes
 - Pilot (data free) component
 - Data (modulated) component
 - FEC
 - Bigger bandwidth
 - Will provide compatibility and interoperability with GNSS

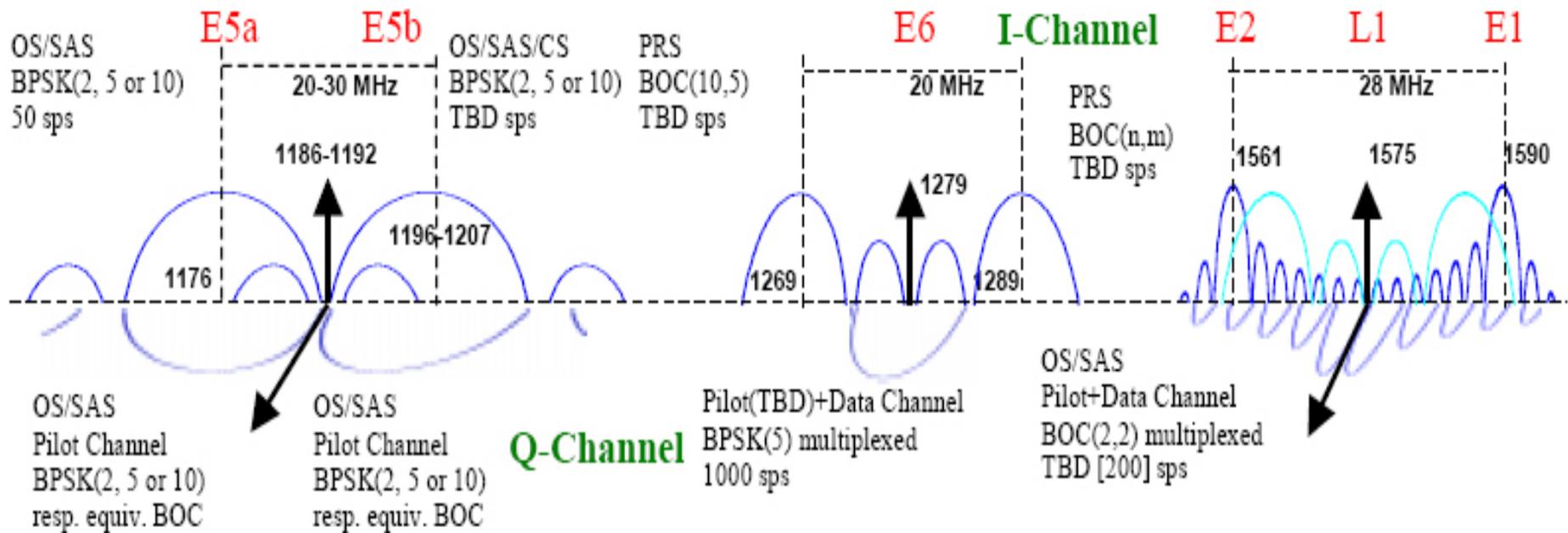


Forward error correction (FEC) - it is used to correct bit decision errors suffered while demodulating the navigation message.

The GNSS

GALILEO SIGNALS

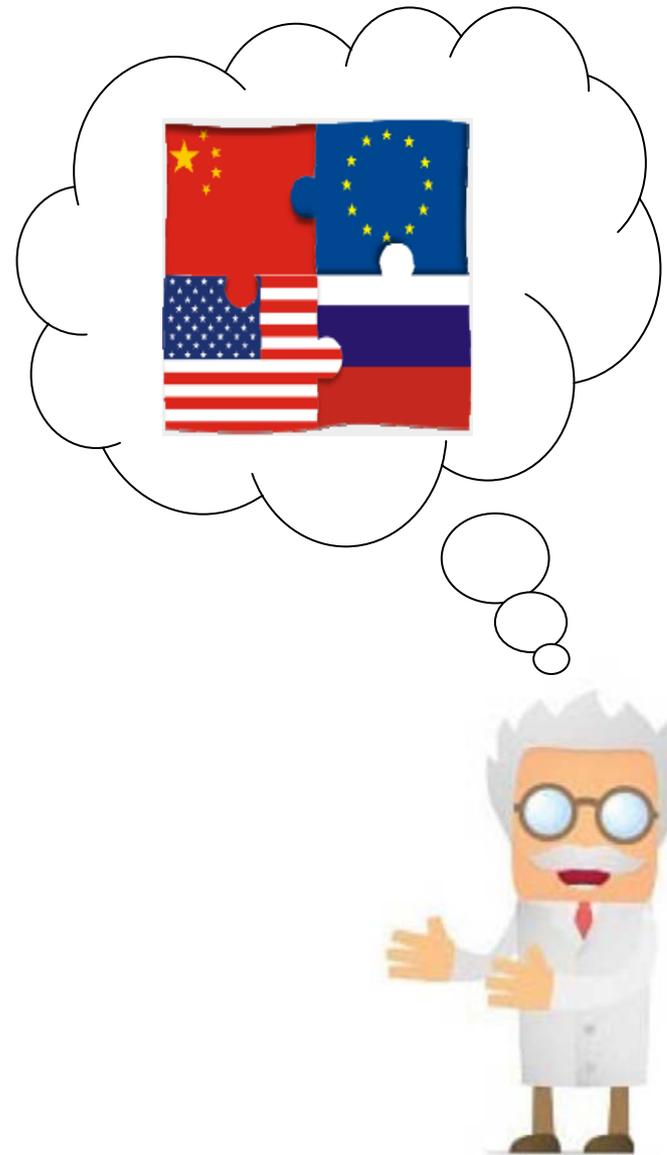
GALILEO frequency spectrum



The GNSS

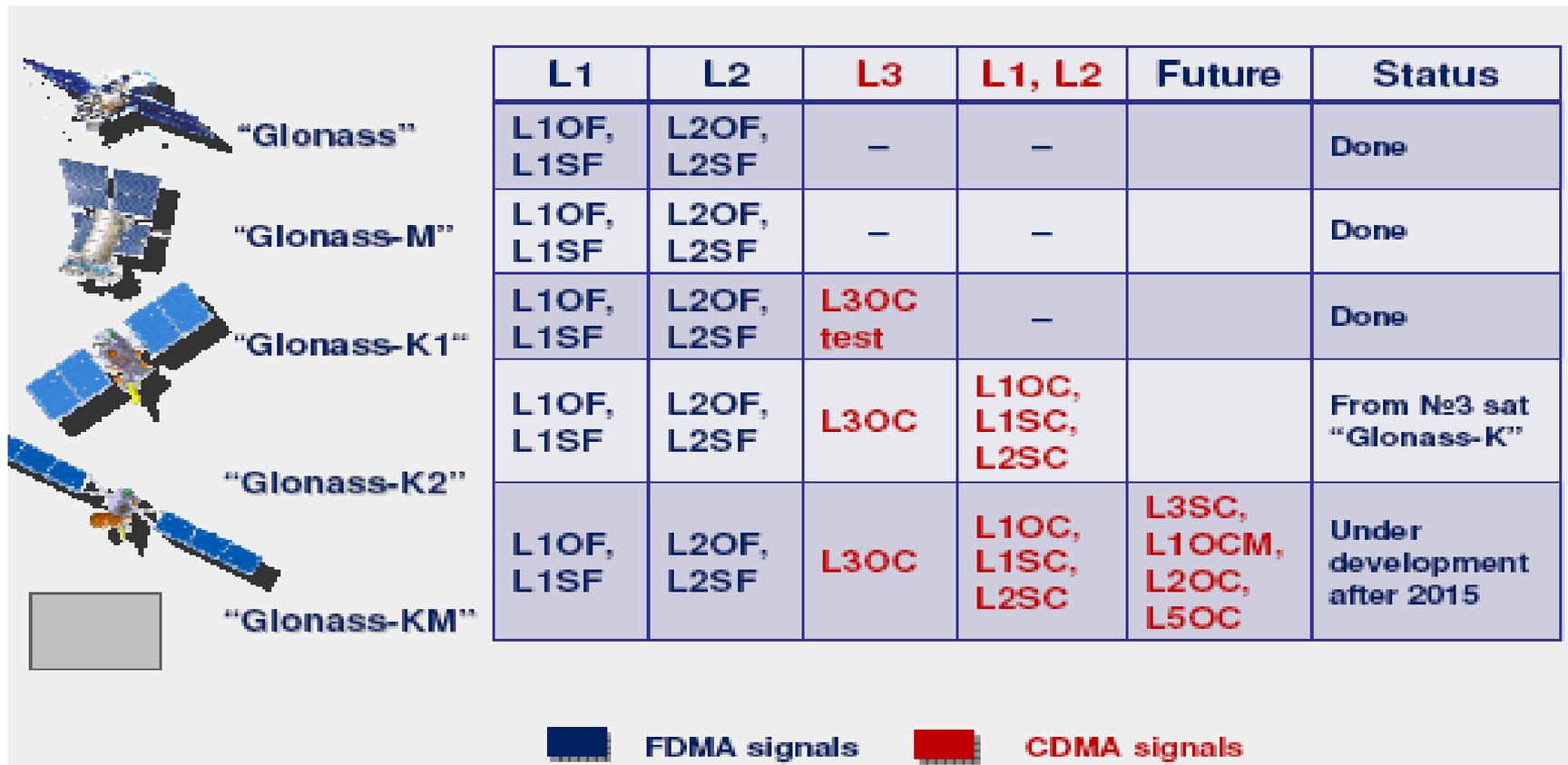
GALILEO SIGNALS

- Characteristics of new *GALILEO* signals:
 - Different PRN codes
 - Longer codes
 - Faster codes (10x)
 - Pilot (data free) component
 - Data (modulated) component
 - Bigger bandwidth (20,46 MHz)
 - New modulation schemes
 - New services:
 - Open service
 - Commercial service
 - Safety of life service



The GNSS

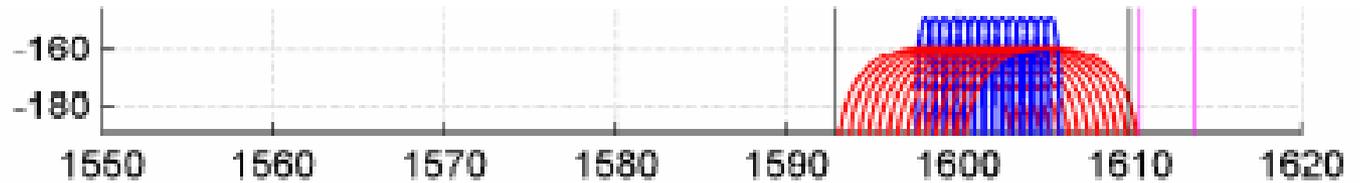
GLONASS SIGNALS



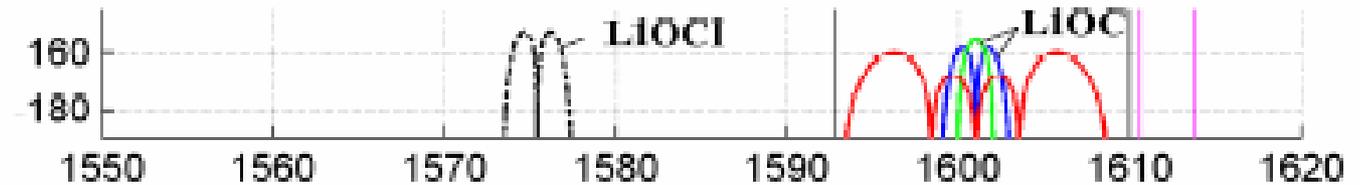
The GNSS

GLONASS SIGNALS

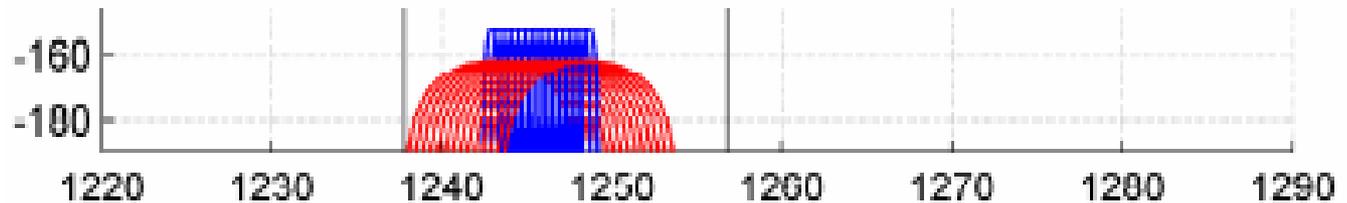
The old
L1OF
signal



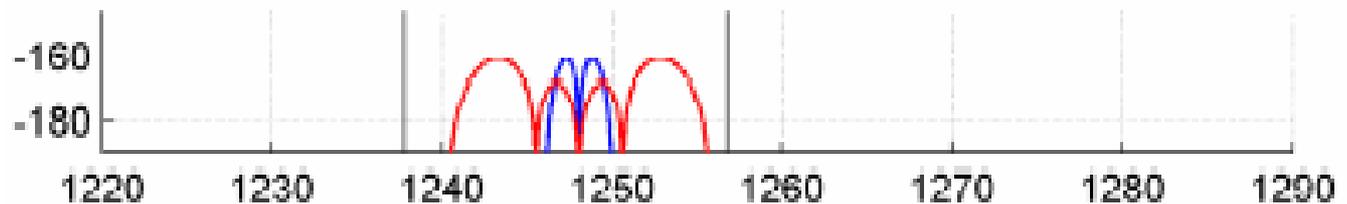
The new
L1OC
signal



The old
L2OF
signal



The new
L2OC
signal



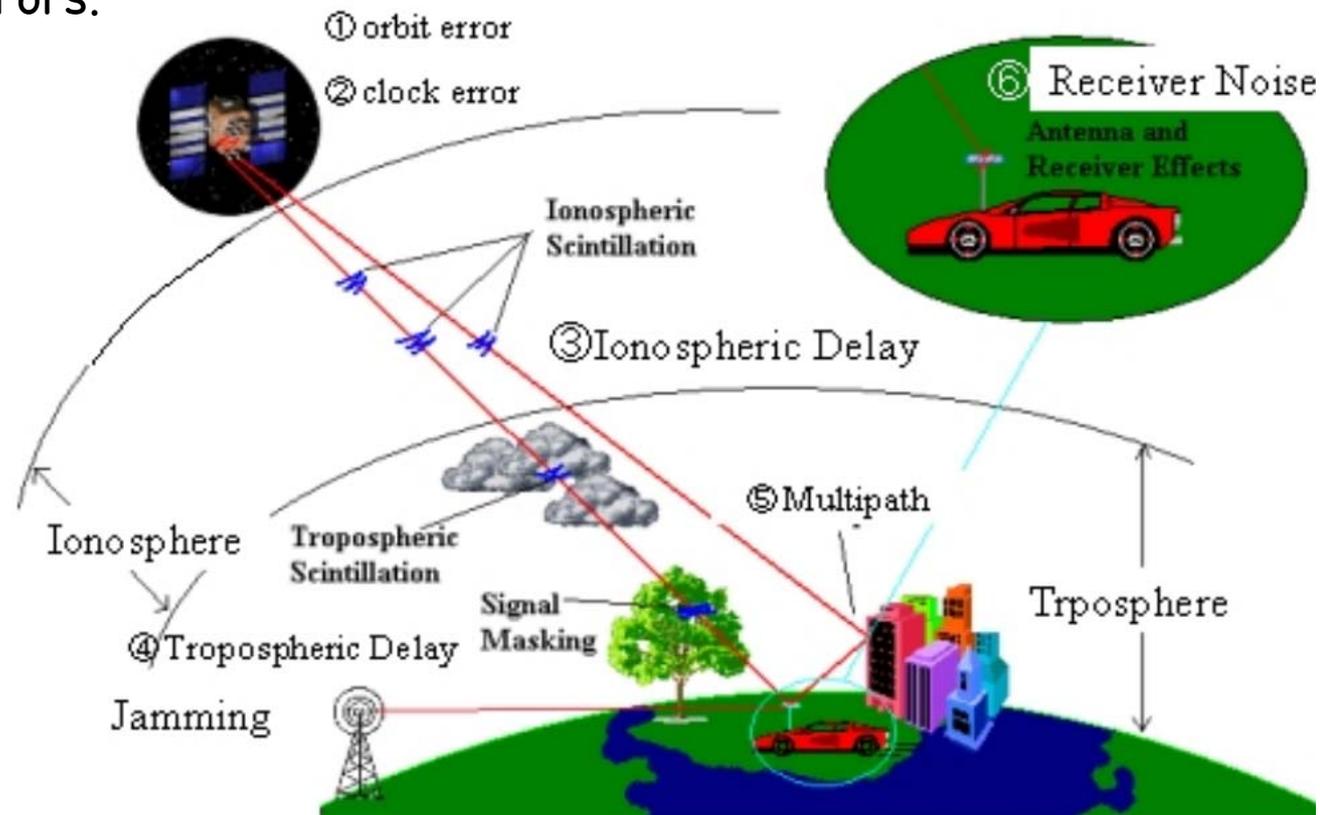
-
- The Ionosphere
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 - **The ionospheric effects on GNSS signals**
 - Methods to reduce the ionospheric impact on GNSS
 - Future goals

The ionospheric effects

GNSS Positioning Errors:

- Weaker geometry.
- Large positioning errors.

Error Sources



The ionospheric effects

Ionospheric delay

Effects proportional to TEC:

- Group Delay
- Phase Advance
- Doppler Shift
- Faraday Rotation
- Ray-path bending

Ionospheric scintillations

- Random fluctuations, in both amplitude and phase

TOTAL ELECTRON CONTENT (TEC) is the total number of electrons present along a path between two points, with units of electrons per square meter, where 10^{16} electrons/m² = 1 TEC unit (TECU).

$$TEC = \int_{ray_path} N_e ds$$

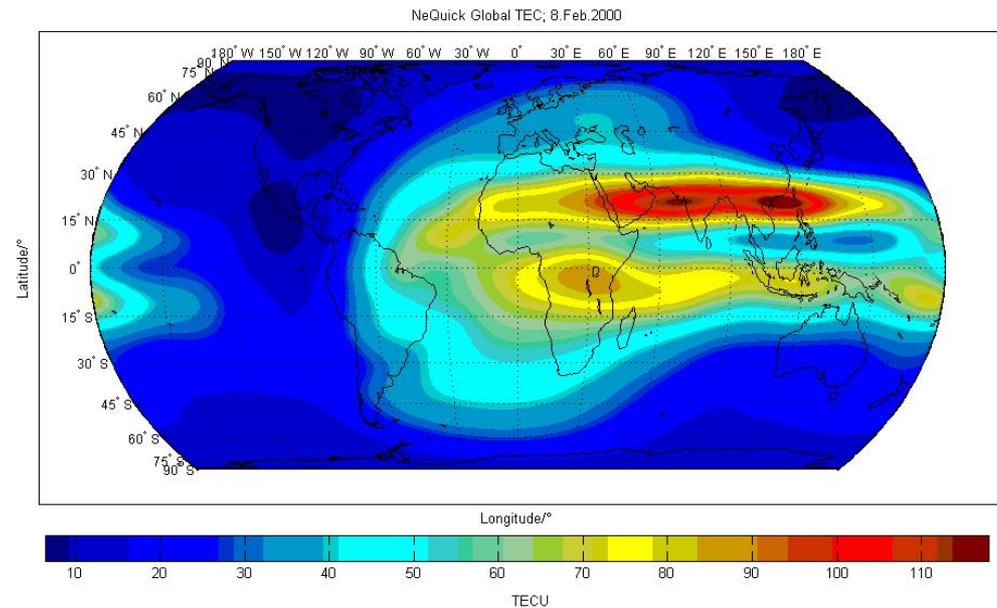
-
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Methods to reduce the ionospheric impact on GNSS

- Using one frequency:
 - Klobuchar model (GPS)
 - NeQuick model (GALILEO)

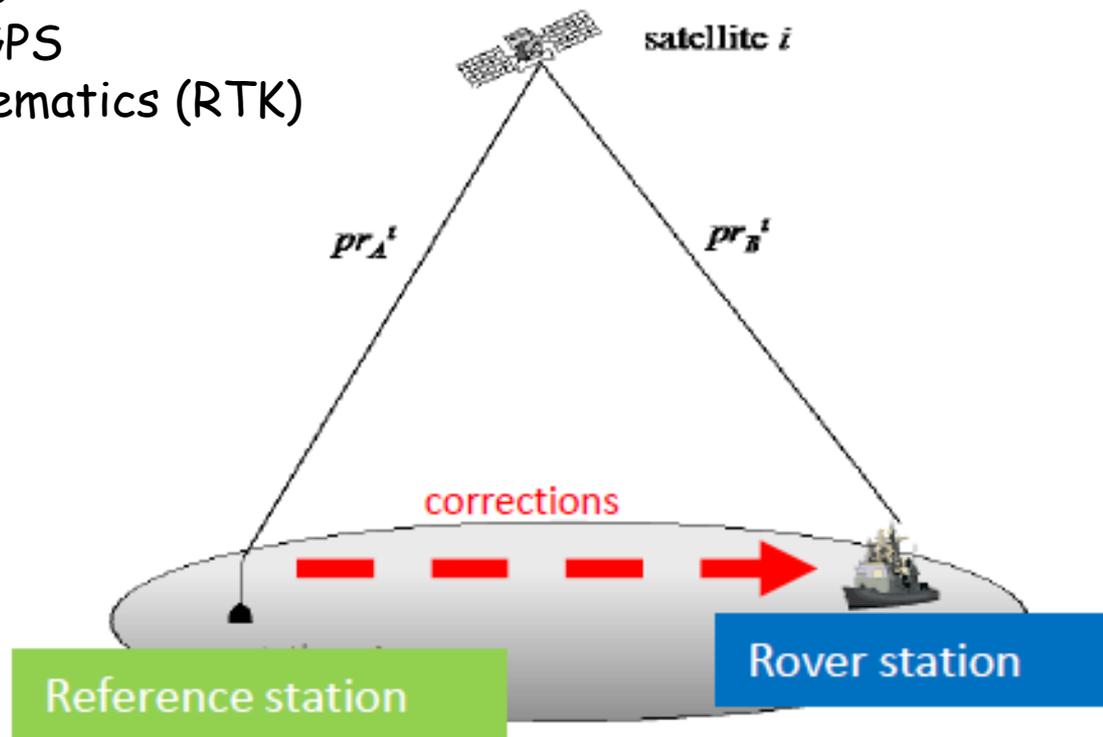
Correct for approximately 50% of the ionospheric range delay.

Allows calculation of the electron concentration at any given location in the ionosphere.



Methods to reduce the ionospheric impact on GNSS

- Using two frequencies
 - Differential GPS
 - Real Time Kinematics (RTK)



Methods to reduce the ionospheric impact on GNSS

- Pseudo range IONO FREE

$$P_{k,L1}^p = \rho_k^p - cdt_k + c(dt^p + T_{GD}) + I_{k,L1}^p + A_k^p + M_{k,L1}^p + HD_{k,L1} + HD^{p,L1} + \varepsilon_p$$

$$P_{k,L2}^p = \rho_k^p - cdt_k + c\left(dt^p + T_{GD} \frac{L_1^2}{L_2^2}\right) + I_{k,L2}^p + A_k^p + M_{k,L2}^p + HD_{k,L2} + HD^{p,L2} + \varepsilon_p$$



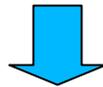
$$P_{k,IF}^p = \rho_k^p - c(dt_k - dt^p) + A_k^p + M_{k,IF}^p + HD_{k,IF} + HD^{p,IF} + \varepsilon_p$$

Methods to reduce the ionospheric impact on GNSS

- Carrier phase IONO FREE

$$\Phi_{k,L_1}^p = [\rho_k^p] \bmod_{\lambda} + \lambda N_{k,L_1}^p - cdt_k + cdt^p - I_{k,L_1}^p + A_k^p + M_{k,L_1,\varphi}^p + HD_{k,L_1,\varphi} + HD^{p,L_1,\varphi} + \varepsilon_{L_1,\varphi}$$

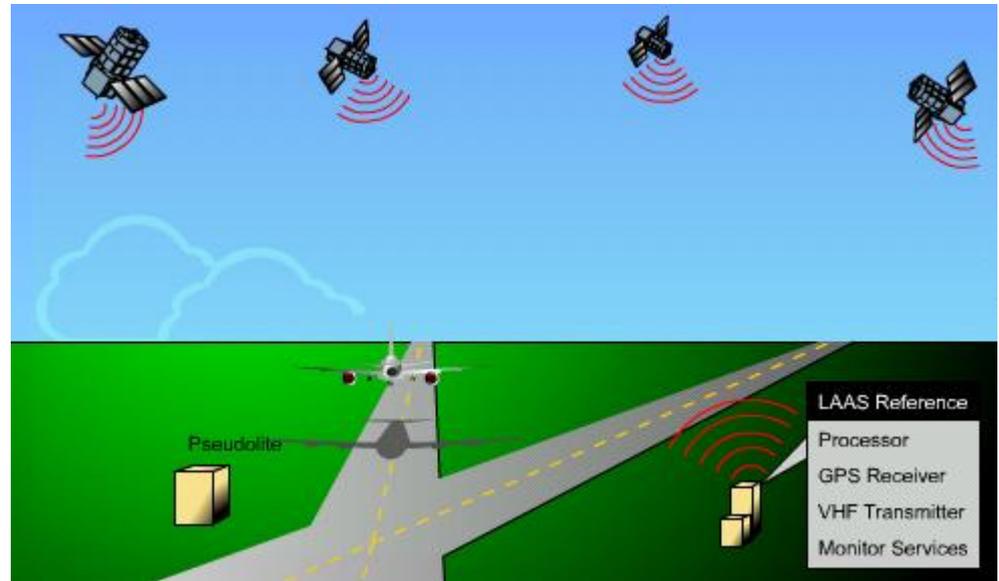
$$\Phi_{k,L_2}^p = [\rho_k^p] \bmod_{\lambda} + \lambda N_{k,L_2}^p - cdt_k + cdt^p - I_{k,L_2}^p + A_k^p + M_{k,L_2,\varphi}^p + HD_{k,L_2,\varphi} + HD^{p,L_2,\varphi} + \varepsilon_{L_2,\varphi}$$



$$\Phi_{k,IF}^p = [\rho_k^p] \bmod_{\lambda} + \lambda N_{k,IF}^p - c(dt_k - dt^p) + A_{k,\Phi}^p + M_{k,IF,\Phi}^p + HD_{k,IF,\Phi} + HD^{p,IF,\Phi} + \varepsilon_{\Phi}$$

Methods to reduce the ionospheric impact on GNSS

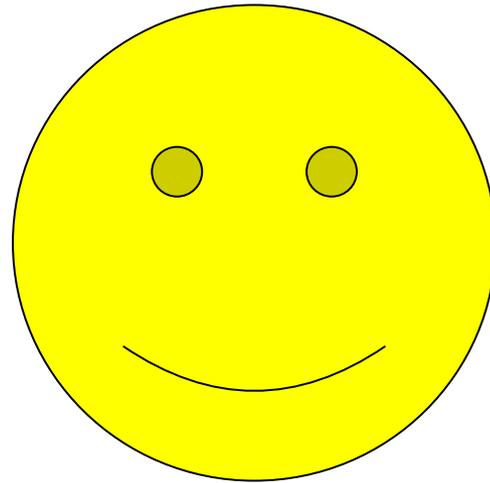
- Benefits from new GNSS signals:
 - New special applications:
 - Open service
 - Commercial service
 - Safety of life service
 - Better accuracy (up to 1 cm)
 - Operation at low signal to noise ratio
 - Better multi-path mitigation capabilities
 - More robust navigation



-
- The Ionosphere
 - The GNSS
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 - **Future goals**

Future goals

- Will investigate the effects of small scale plasma density structures on new signals by taking into account their architecture and the consequent demodulation schemes.
- Will investigate the main threats to the reliable and safe operation of GNSS.
- Will work on new data processing, commercial and scientific applications algorithms.



Thanks for listening